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MVA Course Introduction to Statistical Learning

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Lecture 1

Course objectives

- Introduction to the mathematical foundations of machine learning
- Setup a learning problem to better address users' expectations and constraints
- Get insights to understand the key principles of shallow machine learning methods

Practical information about the course

• Course website :

http://nvayatis.perso.math.cnrs.fr/ISLcourse.html

- Schedule and location
 - Location : ENS Paris-Saclay
 - Dates : Check the online agenda
 - Classroom : Check out the agenda regularly
 - Format : 7 lectures + 4 exercise sessions + personal research
 - Office hours : on demand

• Evaluation :

• Two mandatory exams : Mid-term exam M + final exam F

- Final grade G = max (F; (F+M)/2)
- Mid-term on November 5 am
- Final exam on January 7 am

Course overview

- Chapter 1 : Optimality in statistical learning
 Data / Objectives / Optimal elements / ERM
- Chapter 2 : Mathematical foundations of statistical learning Concentration inequality / Complexity measures / Regularization
- Chapter 3 : Consistency of mainstream machine learning methods

Boosting, SVM, Neural networks / Bagging, Random forests

Chapter 1 - Optimality in statistical learning

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Overview of Chapter 1

- Modeling the data :
 - a probabilistic view
- Modeling the prediction objective :
 - performance *metrics* and risk functionals for prediction
- The goal of learning :
 - optimal elements
- The mother of most Machine Learning algorithms :
 - ERM : Empirical Risk Minimization

Chapter 1 A. Modeling classification data

Generative vs. discriminative

- (X, Y) random pair with distribution P over $\mathbb{R}^d imes \{-1, +1\}$
- 1 Generative view Joint distribution P as a mixture
 - Class-conditional densities : f₊ and f₋
 - Mixture parameter : p = P{Y = +1}
- **2** Discriminative view Joint distribution *P* described by (P_X, η)
 - Marginal distribution : $X \sim P_X = df_X/d\lambda_d$
 - Posterior probability function :

$$\eta(x) = \mathbb{P}\{Y = 1 \mid X = x\}, \quad \forall x \in \mathbb{R}^d$$

- Marginal distribution of X has density : $f_X = pf_+ + (1-p)f_-$
- Posterior probability is given by : $\eta = pf_+/f_X$

Exercise

Find the expressions of $\mathit{f}_+, \mathit{f}_-$ and η in the following probabilistic models :

• Discriminant Analysis : find η knowing

$$f_+ = \mathcal{N}_d(\mu_+, \Sigma_+), f_- = \mathcal{N}_d(\mu_-, \Sigma_-)$$

• Logistic regression : find f_+ , f_- knowing

$$\log\left(\frac{\eta_{\theta}(x)}{1-\eta_{\theta}(x)}\right) = h(x,\theta) , \text{ typically } h(x,\theta) = \theta^{T} x$$

Chapter 1 B. Optimality in the binary classification objective

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Classifier, Error measure, Optimal Elements

- Classifier : $g : \mathbb{R}^d \to \{-1, +1\}$
- Classification error : $L(g) = \mathbb{P} \{ g(X) \neq Y \}$

$$L(g) = \mathbb{E}\big(\eta(X) \cdot \mathbb{I}\{g(X) = -1\} + (1 - \eta(X)) \cdot \mathbb{I}\{g(X) = 1\}\big)$$

- Bayes rule : $g^*(x) = 2\mathbb{I}\{\eta(x) > 1/2\} 1$, $\forall x \in \mathbb{R}^d$
- Bayes error : $L^* = L(g^*) = \mathbb{E}\{\min(\eta(X), 1 \eta(X))\}$
- Excess risk :

$$L(g) - L^* = 2\mathbb{E}\left\{\left|\eta(X) - \frac{1}{2}\right| \cdot \mathbb{I}\left\{g(X) \neq g^*(X)\right\}\right\}$$

Link with parametrics : Plug-in methods do the job but...

- Let $\hat{\eta}$ an estimate of the posterior η based on a sample D_n (e.g. LDA/QDA, logistic regression)
- Consider \widehat{g} a plug-in estimator based on $\widehat{\eta}$

$$\widehat{g}(x) = 2\mathbb{I}\{\widehat{\eta}(x) > 1/2\} - 1 \;, \;\;\; orall x \in \mathbb{R}^d$$

• We have, conditionally on the sample D_n :

$$L(\widehat{g}) - L^* \leq 2\mathbb{E}_X(|\widehat{\eta}(X) - \eta(X)|)$$

- But estimation of η for high dimensional data suffers of the curse of dimensionality !
- Q : Do we really need to estimate η ?

Chapter 1 C. Convex risk minimization

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Convex Risk Minimization (CRM)

- Binary classification data with $Y \in \{+1, -1\}$
- Real-valued decision rule (soft classifier) $f : \mathbb{R}^d \to \mathbb{R}$
- Cost function $arphi~:~\mathbb{R}
 ightarrow\mathbb{R}_+$ convex, increasing, arphi(0)=1
- Expected φ -risk :

$$A(f) = \mathbb{E}\left(\varphi(-Y \cdot f(X))\right)$$

Main examples :

$$\varphi(x) = e^x, \ \log_2(1+e^x), \ (1+x)_+$$

• Note that : $L(\operatorname{sgn}(f)) \leq A(f)$

Exercise

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Find the optimal elements for convex risk minimization :

$$f^* = \operatorname*{arg\,min}_f A(f) \;, \;\; A^* = A(f^*)$$

in the following examples :

(i)
$$\varphi(u) = \exp(u)$$

(ii) $\varphi(u) = \log_2(1 + \exp(u))$
(iii) $\varphi(u) = (1 + u)_+$

Zhang's lemma

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- Assumption (A1) : φ positive, convex, increasing, such that $\varphi(0)=1$
- Set the 'entropy' function :

$$H(\eta) = \inf_{lpha \in \mathbb{R}} (\eta \varphi(-lpha) + (1 - \eta) \varphi(lpha))$$

• Assumption (A2) : $\exists s \geq 1$ and c > 0 such that $orall u \in (0,1)$,

$$\left|\frac{1}{2}-u\right|^{s}\leq c^{s}(1-H(u))$$

 Under (A1-A2), we have, for some s > 1, that any real-valued measurable f satisfies :

$$L(g_f) - L^* \le 2c(A(f) - A^*)^{1/s}$$

Risk communication (1) : Zhang (2004)

• Classifier obtained by CRM :

$$g_{f^*}(x) = 2\mathbb{I}\{f^*(x) > 0\} - 1$$

• Result : if $\varphi \in \{\exp, \operatorname{logit}, \operatorname{hinge}, \ldots\}$, then

 $g_{f^*} = g^*$ (Bayes rule)

• Zhang's lemma : if $\varphi \in \{\exp, \operatorname{logit}\}$, then

$$L(g_f) - L^* \leq \sqrt{2}(A(f) - A^*)^{1/2}$$

• Zhang's lemma : if $\varphi = \text{hinge}$, then

$$L(g_f) - L^* \leq A(f) - A^*$$

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Risk communication (2) : Bartlett, Jordan, and McAuliffe (2006)

• Set the 'entropy' function :

$$\mathcal{H}(\eta) = \inf_{lpha \in \mathbb{R}} (\eta \varphi(-lpha) + (1 - \eta) \varphi(lpha))$$

• ... and the one-sided version :

$$H^{-}(\eta) = \inf_{\alpha:\alpha(2\eta-1)\leq 0} (\eta\varphi(-\alpha) + (1-\eta)\varphi(\alpha))$$

• Define the communication funtion :

$$\psi(x) = H^{-}\left(\frac{1+x}{2}\right) - H^{-}\left(\frac{1-x}{2}\right)$$

• Control of excess risk with ψ^{-1} :

$$L(g_f) - L^* \le \psi^{-1}(A(f) - A^*)$$

and φ convex implies $\lim_{0^+}\psi^{-1}=0$. In the set of the se

Chapter 1 D. Empirical Risk Minimization

Supervised learning setup

- Goal of learning : an optimal decision function $h^* : \mathcal{X} \to \mathcal{Y}$ \mathcal{X} : domain set, \mathcal{Y} : label set
- Input of learning :
 - Training data : a set of labeled data

$$D_n = \{(X_1, Y_1), \ldots, (X_n, Y_n)\}$$

of size *n*, where the (X, Y)'s are in $\mathcal{X} \times \mathcal{Y}$

- Hypothesis space : a collection \mathcal{H} of candidate decision functions $h : \mathcal{X} \to \mathcal{Y}$
- Output of learning : an empirical decision function \hat{h} in the hypothesis space \mathcal{H} estimated from training data D_n
- Reference in \mathcal{H} : the best decision function \bar{h} in the class (the more data, the closer \hat{h} to \bar{h})

The ERM principle Definition

- Loss function : $\ell : \mathcal{Y} \times \mathcal{Y} \rightarrow [0, +\infty]$
- Empirical risk of a decision rule *h* : this is a data-dependent functional

$$\widehat{L}_n(h) = \frac{1}{n} \sum_{i=1}^n \ell(h(X_i), Y_i)$$

• ERM = Empirical Risk Minimization

Learning from training data amounts to solving the following optimization problem

$$\widehat{h}_n = \operatorname*{arg\,min}_{h\in\mathcal{H}} \widehat{L}_n(h)$$

where the minimization is restricted to the hypothesis space.

The notion of *true* error

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• Assumption :

(X, Y) is a pair of random variables with joint distribution P

• True error of a decision rule *h* : this is a distribution-dependent functional

$$L(h) = \mathbb{E}(\ell(h(X), Y)) = \int \ell(h(x), y) dP(x, y)$$

Optimal elements, consistency and bounds

• Bayes rule *h*^{*} and Bayes error *L*^{*}

$$h^* = \operatorname*{arg\,min}_h L(h)$$
 and $L^* = L(h^*)$

- (Strong) Consistency of an inference principle \hat{h}_n $L(\hat{h}_n) \rightarrow L^*$, almost surely
- The nonasymptotic bounds Eldorado :

$$L(\widehat{h}_n) - L^* \leq U(n, \mathcal{H})$$
 whp

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Estimation vs. approximation error Extension of bias-variance decomposition

- Proof idea : Add and retrieve $\widehat{L}_n(\widehat{h}_n)$, $\widehat{L}_n(\overline{h})$, $L(\overline{h})$, then use the definition of ERM to upper bound the sum. Difference between L and \widehat{L}_n appear twice.
- We have :

$$L(\widehat{h}_{n}) - L^{*} \leq \underbrace{2 \sup_{h \in \mathcal{H}} |L(h) - \widehat{L}_{n}(h)|}_{estimation (stochastic)} + \underbrace{L(\overline{h}) - L^{*}}_{approximation (deterministic)}$$

The key trade-off in Machine Learning

- Denote by L(h) the error measure for any decision function h
- We have : $L(\bar{h}) = \inf_{\mathcal{H}} L$, and $L(h^*) = \inf L$
- Bias-Variance type decomposition of error for any output \widehat{h} :



Chapter 1 E. Some other supervised learning problems

From plain classification to...

- Classification in real life : multiclass classification, asymmetric cost, classification with mass constraint, classification with reject option, Neyman-Pearson classification
- Preference learning
- Scoring
- Regression

Variations on binary classification

• Asymmetric cost - set $\omega \in (0,1)$,

$$\begin{split} L_{\omega}(g) &= 2\mathbb{E}\big((1-\omega)\mathbb{I}\{Y=+1\}\mathbb{I}\{g(X)=-1\} \\ &+ \omega\mathbb{I}\{Y=-1\}\mathbb{I}\{g(X)=+1\}\big) \end{split}$$

• Classification with mass constraint - set $u \in (0,1)$

 $\min_{g} \mathbb{P}(Y \neq g(X))$ subject to $\mathbb{P}(g(X) = 1) = u$

(Refer to Clémençon and Vayatis (2007))

• Classification with reject option - set $\gamma \in (0, 1/2)$

$$L^R_d(g) = \mathbb{P}(Y
eq g(X) \ , \ g(X)
eq \mathbb{R}) + \gamma \mathbb{P}(g(X) = \mathbb{R})$$

(Refer to Herbei and Wegkamp (2006))

Which decision?

Build a decision rule to be evaluated on a new sample

1 Predictive Classification

Given a new X', predict the label Y' Decision rule : g : $\mathbb{R}^d \rightarrow \{-1, +1\}$ Happy if classification error rate is low on average

2 Predictive Ranking/Scoring Given new data $\{X'_1, \ldots, X'_m\}$, predict a ranking $(X'_{i_1}, \ldots, X'_{i_m})$ Decision rule : $s : \mathbb{R}^d \to \mathbb{R}$ that defines the permutation (i_1, \ldots, i_m) Happy if $(Y'_{i_1}, \ldots, Y'_{i_m})$ is "close" to a decreasing sequence

Goal : Define an order on \mathbb{R}^d from binary label information

Coming next

Next lecture :

- Discuss the case of different prediction objectives
- What is the complexity of learning
- Mathematical tools
- \Rightarrow Homework \rightarrow Prepare Exercise Set #1