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Introduction to Statistical Learning

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Lecture # 5 - Statistical analysis of mainstream ML algorithms

Part I - Margin bounds and application to SVM

Machine Learning Methods

Optimization is central

Some popular examples :

- Sparse linear models \rightarrow convex optimization (gradient methods)
- Kernel ridge regression \rightarrow convex optimization (quadratic optimization)
- Deep learning \rightarrow nonconvex optimization (stochastic gradient descent) + implicit regularization (tricks)

At the end of the day :

loss+training data+functional class+optimization \rightarrow random rule \hat{f}_n

Main theoretical objectives of the course

- Take a well-known ML algorithm which operates in \mathcal{F} : it produces a (random) sequence of decision rules $(\hat{f}_n)_{n \geq 1}$ in \mathcal{F} . Then show :
- **Convergence of estimation error :**

$$L(\hat{f}_n) \rightarrow \inf_{\mathcal{F}} L \text{ almost surely as } n \rightarrow \infty ,$$

- **Upper bounds :** with probability at least $1 - \delta$, there exists some constant c such that :

$$L(\hat{f}_n) - \inf_{\mathcal{F}} L \leq C(\mathcal{F}, n) + c \sqrt{\frac{\log(1/\delta)}{n}} ,$$

where $C(\mathcal{F}, n) = O(1/\sqrt{n})$ after processing some complexity/stability measure

Key principle to lower bias : Regularized optimization

- Objective : aim at consistency $L(\hat{f}_n) \rightarrow L^*$ almost surely as $n \rightarrow \infty$.
- Take \mathcal{F} a *very large* space and define a proper penalty term :

$$C_n(f) = \underbrace{\hat{L}_n(f)}_{\text{Training error}} + \lambda \underbrace{\text{pen}(f, n)}_{\text{Regularization}}$$

- Example : ridge regression where $f(x) = \theta^T x$:
 $\hat{L}_n(f) = \frac{1}{n} \sum_{i=1}^n (Y_i - \theta^T X_i)^2$ and $\text{pen}(f, n) = \frac{1}{n} \|\theta\|_2^2$
- The penalty grows with the complexity of f and vanishes when $n \rightarrow \infty$

Overview of Chapter 3

1. Consistency of local methods :
 - a. k-Nearest Neighbors
 - b. (decision trees)
 - c. (local averaging)
2. Consistency of global methods
 - a. Support Vector Machines
 - b. Boosting
 - c. Neural networks
3. Consistency of ensemble methods
 - + Bagging, Random Forests

1. Local methods

The example of k -Nearest neighbors (k -NN)

Problem considered (Multiclass) Classification

- Given :
 - Consider a sample of classification data

$$(X_1, Y_1) \dots (X_n, Y_n)$$

where $X_i \in \mathbb{R}^d$ vector of independent variables,
 $Y_i \in \{1, \dots, C\}$ the label

- Want :
 - to predict the label y at any position x

k -Nearest Neighbor (1/4)

Principle of the k -NN algorithm

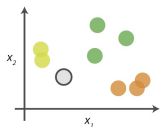
- 1 Compute distances
 - Compute pairwise distances $d(x, X_i)$ for all $i = 1, \dots, n$
- 2 Sort training data
 - Sort the data points from the closest $X_{(1)}$ to the farthest $X_{(n)}$ (i.e. $d(x, X_{(1)}) \leq \dots \leq d(x, X_{(n)})$)
- 3 Prediction $\hat{h}(x, k) =$ Majority vote of the k -NN
 - Consider the labels $Y_{(1)}, \dots, Y_{(k)}$ of the k closest points to x and take the majority vote
$$\hat{h}(x, k) = \arg \max_c \left\{ \sum_{l=1}^k \mathbb{I}\{Y_{(l)} = c\} \right\}$$

k -Nearest Neighbor (2/4)

Principle of the k -NN algorithm

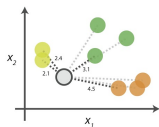
kNN Algorithm

0. Look at the data



Say you want to classify the grey point into a class. Here, there are three potential classes - lime green, green and orange.

1. Calculate distances



Start by calculating the distances between the grey point and all other points.

2. Find neighbours

Point	Distance	
	2.1	→ 1st NN
	2.4	→ 2nd NN
	3.1	→ 3rd NN
	4.5	→ 4th NN

Next, find the nearest neighbours by ranking points by increasing distance. The nearest neighbours (NNs) of the grey point are the ones closest in dataspace.

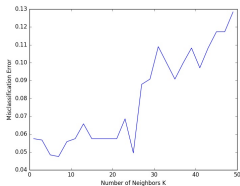
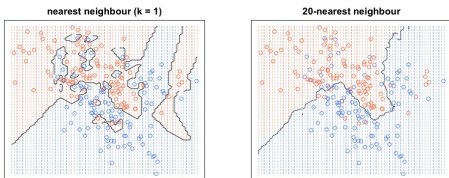
3. Vote on labels

Class	# of votes	
	2	→ Class wins the vote! Point is therefore predicted to be of class .
	1	
	1	

Vote on the predicted class labels based on the classes of the k nearest neighbours. Here, the labels were predicted based on the $k=3$ nearest neighbours.

Nearest Neighbors (3/4) Hyperparameters

- Choice of a distance d between points of \mathbb{R}^d
- Number k of Nearest Neighbors, estimated by cross-validation :



k -Nearest Neighbor (4/4) Theory

- Recall : classification error $L(h) = \mathbb{P}(Y \neq h(X))$ and $L^* = \inf L$
- Consistency result :

$$\mathbb{E}L(\hat{h}(\cdot, k_n)) \rightarrow L^*$$

under the condition : $k_n \rightarrow \infty$ and $k_n/n \rightarrow 0$ when $n \rightarrow \infty$

- No closed-form solution for optimal k_n (in practice, we use cross-validation)
- No theoretical clue on the choice of the distance (related to data representation and the physics of the problem)

Interlude - Some tools

Definition of Margin Loss, Contraction Principle,
Concentration Inequality

Margin loss

- Fix $\rho > 0$
- The *margin loss* is defined, for any $u, v \in \mathbb{R}$, as :
 $\ell(u, v) = m_\rho(uv)$ where

$$m_\rho(t) = \begin{cases} 0 & \text{if } \rho \leq t \\ 1 - \frac{t}{\rho} & \text{if } 0 \leq t \leq \rho \\ 1 & \text{if } t \leq 0 \end{cases}$$

- Empirical margin error on a sample D_n :

$$\hat{L}_{n,\rho}(f) = \frac{1}{n} \sum_{i=1}^n m_\rho(Y_i f(X_i))$$

Contraction principle

Theorem. (Ledoux, Talagrand (1991))

Consider $\psi : \mathbb{R} \rightarrow \mathbb{R}$ a Lipschitz function with constant κ

Then, for any class \mathcal{F} of real-valued functions, we have :

$$\widehat{R}_n(\psi \circ \mathcal{F}) \leq \kappa \widehat{R}_n(\mathcal{F})$$

Reminder from Chapter 2

Uniform bound with Rademacher average

Proposition.

Consider \mathcal{F} a class of functions from \mathcal{Z} to $[0, 1]$

Then, with probability at least $1 - \delta$:

$$\sup_{f \in \mathcal{F}} \left(\mathbb{E}(f(Z_1)) - \frac{1}{n} \sum_{i=1}^n f(Z_i) \right) \leq 2R_n(\mathcal{F}) + \sqrt{\frac{\log(1/\delta)}{2n}}$$

and

$$\sup_{f \in \mathcal{F}} \left(\mathbb{E}(f(Z_1)) - \frac{1}{n} \sum_{i=1}^n f(Z_i) \right) \leq 2\hat{R}_n(\mathcal{F}) + 3\sqrt{\frac{\log(2/\delta)}{2n}}$$

2. Consistency of global methods

a. Support Vector Machines

Principle of Support Vector Machines

- Kernel $k : \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$ symmetric and positive
- Reproducing Kernel Hilbert Space $(\mathcal{H}_k, \langle \cdot, \cdot \rangle)$ corresponding to kernel k .
- Class of functions/classifiers : $g = \text{sgn}(h)$ where

$$h \in \mathcal{H}(X) \doteq \left\{ h = \sum_{i=1}^n \alpha_i k(X_i, \cdot) : \alpha_1, \dots, \alpha_n \in \mathbb{R} \right\} \subset \mathcal{H}_k$$

- Optimization problem : set $\lambda > 0$

$$\hat{h}_\lambda = \arg \min_{\mathcal{H}_k} \left\{ \sum_{i=1}^n (1 - Y_i h(X_i))_+ + \lambda \|h\|_k \right\}$$

RKHS theory in a nutshell

Theorem.

Let $k : \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$ a kernel that is symmetric and positive.

Then, there exists :

- a Hilbert space $(\mathcal{H}_k, \langle \cdot, \cdot \rangle)$, called the Reproducing Kernel Hilbert Space
- a mapping $\Phi : \mathbb{R}^d \rightarrow \mathcal{H}_k$ such that :

$$\forall u, v \in \mathbb{R}^d, \quad k(u, v) = \langle \Phi(u), \Phi(v) \rangle$$

Plus, we have the reproducing property :

$$\forall h \in \mathcal{H}_k, \quad \forall u \in \mathbb{R}^d, \quad h(u) = \langle h, k(u, \cdot) \rangle$$

and $\|h\|_k = \sqrt{\langle h, h \rangle}$

Key property of SVM

- By the representer's theorem (admitted), it suffices to minimize over $\mathcal{H}(X)$ instead of \mathcal{H}_k
- Note that, if $h \in \mathcal{H}(X)$:

$$\|h\|_k^2 = \sum_{i,j} \alpha_i \alpha_j k(X_i, X_j)$$

Global methods (e.g. CRM)

- Based on empirical minimization of error functionals
- Example in the case of *soft* classifiers $h : \mathbb{R}^d \rightarrow \mathbb{R}$
- Convex risk minimization, with φ positive convex cost function :

$$\hat{A}(h) = \frac{1}{n} \sum_{i=1}^n \varphi(-Y_i h(X_i))$$

- Note that if $h \in \text{span}(\mathcal{H})$ with \mathcal{H} some class of classifiers, then the minimization problem is convex.
- Main issue : complexity of the class \mathcal{H} of candidate decision rules

Rademacher complexity of SVM

Proposition.

Let X_1, \dots, X_n be an n -sample in \mathbb{R}^d , and denote by K the Gram matrix with coefficients $k(X_i, X_j)$, $1 \leq i, j \leq n$.

Introduce the subspace of functions with bounded RKHS norm :

$$\mathcal{F}_M = \{h \in \mathcal{H}_k : \|h\|_k \leq M\}$$

We then have :

$$\widehat{R}_n(\mathcal{F}_M) \leq \frac{M\sqrt{\text{trace}(K)}}{n}$$

In addition, if we have : $k(X_i, X_i) \leq R^2$ for $1 \leq i \leq n$, then

$$\widehat{R}_n(\mathcal{F}_M) \leq \frac{MR}{\sqrt{n}}$$

Margin bounds for SVM classification

Theorem. (Fixed margin)

Let \mathcal{H}_k the RKHS with kernel k .

Fix $\rho \in (0, 1)$, and $\delta > 0$. Then with probability at least $1 - \delta$, we have, for any SVM classifier g :

$$L(g) \leq \hat{L}_{n,\rho}(g) + 2 \left(\frac{MR}{\rho\sqrt{n}} \right) + \sqrt{\frac{\log(1/\delta)}{2n}}$$

and

$$L(g) \leq \hat{L}_{n,\rho}(g) + 2 \left(\frac{M\sqrt{\text{trace}(K)}}{\rho n} \right) + 3\sqrt{\frac{\log(2/\delta)}{2n}}$$